

Development of Manufacturing Features with Advanced Parameterization Possibilities

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### CA Engineering Modeling







### Question: What is the final result of CAEM ?

### Answer: This is NC Data

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### Manufacturers Expressions:

### The Japanese: 6 iterations needed

### **US: Expensive**

### The Germans: Time consuming

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### Statistical issue produced by Dun&Breadstreet





$$\Delta_{\Sigma} = \Delta_{1} + \Delta_{2}$$

 $\Delta_1 - \text{``Expected'' errors conditioned by inaccuracy of Decision} \\ \text{Making Models, inaccuracy of input data, operator faults} \\$ 

 $\Delta_2$  – "Unexpected" errors conditioned by difference between projected and actual values of machine tools, fixtures, cutting tools and workpiece



- $\Delta_1 \mbox{ can be expressed through the determinate models and will be identified and corrected by special models and corresponding software$
- $\Delta_2 {\rm can \ be \ expressed \ through \ the \ stochastic \ models \ while \ influence \ of \ technological \ disturbances \ is \ considerable$



### Investigation of Dimensional fluctuation of workpiece geometry and fluctuation of workpiece Hardness

- 1. Reviewing of engineering hand-books
  - 2. Reviewing of manufacturing experience
    - 3. Reviewing of literature sources



### Engineering hand-books survey

Types	$(R_z)_1$ (mm)	h1 (mm)	$(\Delta \Sigma)_1$ (mm)			(Td)1 (mm)	$\epsilon_1 \text{ (mm)}$
CASTING	0.2	0.1	0.28		4	2.6	
			$\Delta\kappa$	$\Delta$ б		5	4
PUNCHING	0.2	0.25	0.084	Ч	1.1		
ROLLING	0.32	0.4	2.1		3	4.32	
			$\Delta\kappa$	$\Delta$ б			
WELDING	1.5	_	0.06	Ч	1.06	5.5	5.3



### Manufacturing experience survey

Types	$(R_z)_1(mm)$	$h_1(mm)$	$(\Delta \Sigma)_1$ (mm)	$(Td)_1 (mm)$	$\epsilon_1 (\text{mm})$
CASTING	$(R_z)_1$	$h_1$	$(\Delta \Sigma)_1$	4	2.6
PUNCHING	(R <sub>z</sub> ) <sub>1</sub>	$h_1$	$(\Delta \Sigma)_1$	4.2	3.7
ROLLING	-	-	-	_	-
WELDING	(R <sub>z</sub> ) <sub>1</sub>	h <sub>1</sub>	$(\Delta \Sigma)_1$	11	8.1



### Survey of literature sources

Types	$(R_z)_1$ (mm)	h1 (mm)	$(\Delta \Sigma)_1$ (mm)	(Td)1 (mm)	$\epsilon_1 (mm)$
CASTING	(Rz)1	h1	0.21	2.6	1.8
PUNCHING	0.2	1	$(\Delta \Sigma)$ I	2.4	3.5
ROLLING	$(R_z)_1$	0.75	$(\Delta \Sigma)$ 1	(Td)ı	4.7
WELDING	_	3.5	5.6	15.3	16.8

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#### Combined results of dimensional fluctuations

	Hand-Books ɛ <sub>1</sub> (mm)	Experience ɛ <sub>2</sub> (mm)	Sources ɛ <sub>3</sub> (mm)
CASTING	2.6	2.6	1.8
PUNCHING	4	3.7	3.5
ROLLING	4.32	-	4.7
WELDING	5.3	8.1	16.8



#### Fluctuation of workpiece hardness



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### Consideration of standard process of thermal strain-hardening

#### Iron Alloys

		Actual values of Hardnes (HB)			
N⁰	Thermal Conditions	Average Value	Stray Field	Standard Deviation	
1	Отжиг810 <sup>0</sup> – 840 <sup>0</sup> С	154.1	12.3	8.00%	
2	Нормализация 860 <sup>0</sup> – 880 <sup>0</sup> С, выдержка 20 мин.	169.5	6.2	3.60%	
3	Закалка 840 <sup>0</sup> – 860 <sup>0</sup> С, вода отпуск 630 <sup>0</sup> С	190.6	25.8	13.50%	
4	Закалка 840 <sup>0</sup> – 860 <sup>0</sup> С, вода отпуск 630 <sup>0</sup> С	216.3	41.3	19.10%	
5	Закалка 840 <sup>0</sup> – 860 <sup>0</sup> С, вода отпуск 600 <sup>0</sup> С	233.5	53.5	23.00%	
6	Закалка 840 <sup>0</sup> – 860 <sup>0</sup> С, вода отпуск 500 <sup>0</sup> С	265.7	82	30.90%	
7	Закалка 840 <sup>0</sup> – 860 <sup>0</sup> С, вода отпуск 440 <sup>0</sup> С	329.1	148.3	45.10%	

#### **Aluminum Alloys**

		Actual values of Hardnes (HB)			
N⁰	Thermal Conditions	Average Value	Stray Field	Standard Deviation	
1	Отжиг810 <sup>0</sup> – 840 <sup>0</sup> С	147.2	12.5	8.50%	
2	Нормализация 860 <sup>0</sup> – 880 <sup>0</sup> С, выдержка 20 мин.	158.5	9.5	6.00%	
3	Закалка 840 <sup>0</sup> – 860 <sup>0</sup> С, вода отпуск 630 <sup>0</sup> С	182.4	27.3	15.00%	
4	Закалка 840 <sup>0</sup> – 860 <sup>0</sup> С, вода отпуск 630 <sup>0</sup> С	218.1	51.1	23.40%	
5	Закалка 840 <sup>0</sup> – 860 <sup>0</sup> С, вода отпуск 600 <sup>0</sup> С	-	_	-	
6	Закалка 840 <sup>0</sup> – 860 <sup>0</sup> С, вода отпуск 500 <sup>0</sup> С	253.8	116.5	46.00%	
7	Закалка 840 <sup>0</sup> – 860 <sup>0</sup> С, вода отпуск 440 <sup>0</sup> С	248.4	121	48.70%	



### Main Question of Research:

How reduce the  $\Delta_2$  component of error in NC data conditioned by above mentioned disturbances ?

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# Ways of problem solution I. Implementation of preliminary inspected high-precision workpieces Advantage: Decrease dispersion of hardness and geometry and as a result A<sub>2</sub> component of error Disadvantage: Final cost will undesirable especially

for small batch sizes

$$C_{\Sigma} = C_1 + C_2 + \dots + C_n$$





### II. Premeditated diminution of design parameters

Advantage: Ensure the quality of part surfaces, remove the risk of process violation

Disadvantage: Low profitability of using of CNC machine tools



### III. Implementation of real-time Adaptive Control Systems

Advantage: Compensate disturbances by real-time control according to preliminary adjusted rules –  $P_z$ =Const, M=Const, V=Const, etc.

Disadvantage: Fixed rules enables to compensate disturbances in small range of dispersion

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### Implementation of Adaptable Decision Making Models (ADMM) on CAEM

ADMM is determinate model which in addition contains constraint equation between output parameter and disturbances

$$I \longrightarrow \underbrace{\int_{D=\Phi(Q)}^{D=\Phi(Q)} Q}_{D}$$

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### Place of ADMM implementation





### ADMM joins two types of models:

- I. Models for re-calculation of depth of cut and tool path geometry according to actual dimensions of workpiece.
- II. Models for re-determination of cutting conditions according to actual values of depth of cut and workpiece hardness.



### Models activity





### For separation of depth of cut and tool path calculation models it is necessary to formalize typical



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### Two main geometrical structures have been formed:

- STHO the half-open "STAIR"
- STCL the closed "STAIR"



### STHO structure is built on the base of typical constraints of 5 geometrical elements: $P_1 \rightarrow C_1 \rightarrow L_1 \rightarrow C_2 \rightarrow L_2$



 $STHO = \left\{ P_1 \land \left( C_1 \lor L_1 \lor C_2 \right) \lor L_2 \right\}$ 



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### Parameterization scheme of STHO







### Typical structures of STHO

STHO<sub>4-1</sub>  $\Pi_{4-1}^{0} = \{ D_1, \overline{Z_1}, D_3, \overline{Z_3}, D_4, \overline{Z_4} \} \qquad \Pi_{5-6}^{0} = \{ D_1, \overline{Z_1}, R_1, \alpha, \overline{D_4} \}$  $\Pi_{4-1}^{K} = \{R_2 = 0\}$  $\Pi_{4-1}^{H} = \{D_2, Z_2, R_1, \alpha\}$ 



STHO<sub>5-6</sub>

```
\Pi_{5-6}^{K} = \{ D_2 = 0, Z_2 = 0, Z_4 = 0 \} \qquad \Pi_{7-1}^{K} = \{ \}
     \Pi_{5-6}^{H} = \{D_3, Z_3, R_2\}
```



STHO<sub>7-1</sub>  $\Pi_{7-1}^{0} = \{D_1, Z_1, \alpha, R_2, D_3, Z_3, D_4, Z_4\}$  $\Pi_{7-1}^{H} = \{D_2, Z_2, R_1\}$ 



58 typical structures can be generated



### STCL structure is built on the base of composition of half-open stair STHO with its mirror structure



 $\overline{STCL} = \{P_1 \land (C_1 \lor L_1 \lor C_2) \lor L_2 \land (C_3 \lor L_3 \lor C_4)\}$ 

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### Parameterization scheme of STCL



1798 typical structures can be generated

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### On the base of STHO and STCL structures 8 manufacturing shapes for turning was developed

 $Z_{HO}^{E} = \psi(STHO)$ 







### Model I www.cadcam.ge $Z_{CL}^{P} = \psi(\left|STCL\right|_{90^{o}})$ $Z_{CL}^{I} = \psi(|STCL|_{180^{\circ}})$ $Z_{CL}^{E} = \psi(STCL)$ $Z_{OP}^{E} = \psi(|STCL|_{90^{o}})$ $Z_{OP}^{E} = \psi(|STCL|_{180^{\circ}})$ $Z_{OP}^{I} = \psi(STCL)$



Each parametric shape {Z} is associated with cutting tools {T} and corresponding tool movement scheme {P}

Each typical combination of  $\{Z\} \rightarrow \{T\} \rightarrow \{P\}$  brings formalism for development of models of depth of cut and tool path geometry re-calculation (Model I)



By joining the formalism  $\{Z\} \rightarrow \{T\} \rightarrow \{P\}$ with models  $\{M\}$  for re-calculation of cutting conditions according to real-time sensor-based control, final formalism of ADMM will be formulated.



### {M} models are distributed in two groups:

Rough cutting group

 $[V_0S_0] [S_0N] [S_0F] [S_0T] [V_0T]$ 

• Finish cutting group

 $[V_0S_0] [V_0Q] [V_0R_z]$ 



### $[S_0N]$ rule

Make real-time recalculations of cutting speed V in order to ensure constant value of feedrate –  $S_0$  and cutting power - N





ADMM Formalism:  $\{Z\} -> \{T\} -> \{P\} -> \{M\}$ 

For each typical case of turning corresponding manufacturing feature can be formed











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### Manufacturing Features



Shape	Tool	Scheme	Rules
			[V₀S₀] [S₀Z] [S₀F] [S₀T]
			[V₀S₀] [S₀N] [S₀F] [S₀T]

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### Manufacturing Features



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### Manufacturing Features



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### Manufacturing Features







## What we receive finally ?

which enables :



• To built models for re-calculation of depth of cut, tool path geometry and cutting conditions for CNC

• To realize CA process modeling activity adaptable to actual manufacturing conditions

• To organize CA process modeling software architecture and develop the corresponding software tools

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#### AutoCAD/CATIA



### Conclusions

- 1. Process Modeling Adaptive Engineering enables to ensure high reliability of output of CAEM
- 2. Through the ADMM it is possible to enlarge range of disturbances compensation of real-time adaptive control system
- 3. Suggested collection of manufacturing features can be modified by expending the collection of tool or movement scheme, but not by modifying parametric shapes or cutting rules, while they express absolute majority of turning cases.



### Thank You for attention